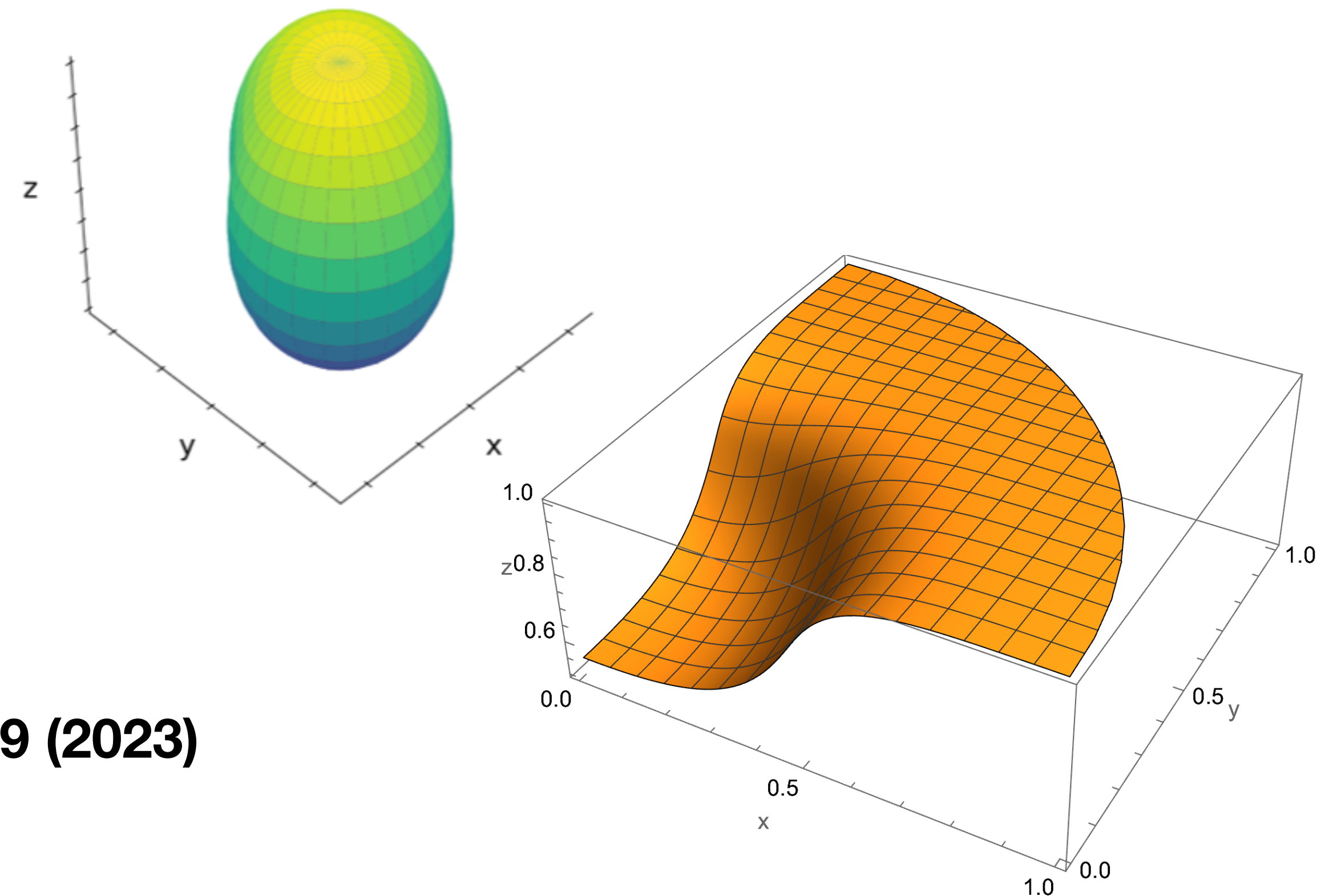




Moment of inertia for axisymmetric neutron stars in the standard model extension

Yiming Dong (Peking University)
ydong@pku.edu.cn

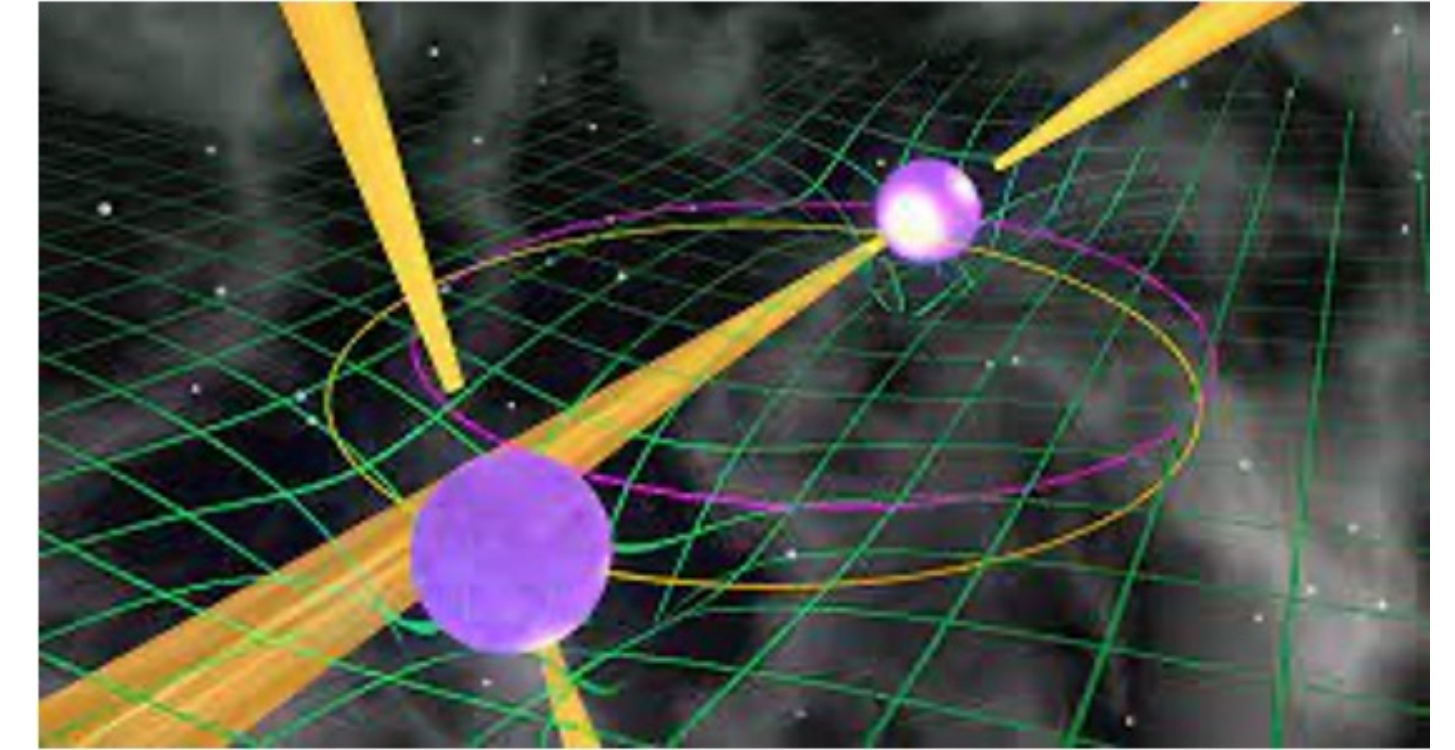
Supervisor: Lijing Shao



Ref: Y. Dong, Z. Hu, R. Xu and L. Shao, PRD 108,104039 (2023)

Moment of inertia

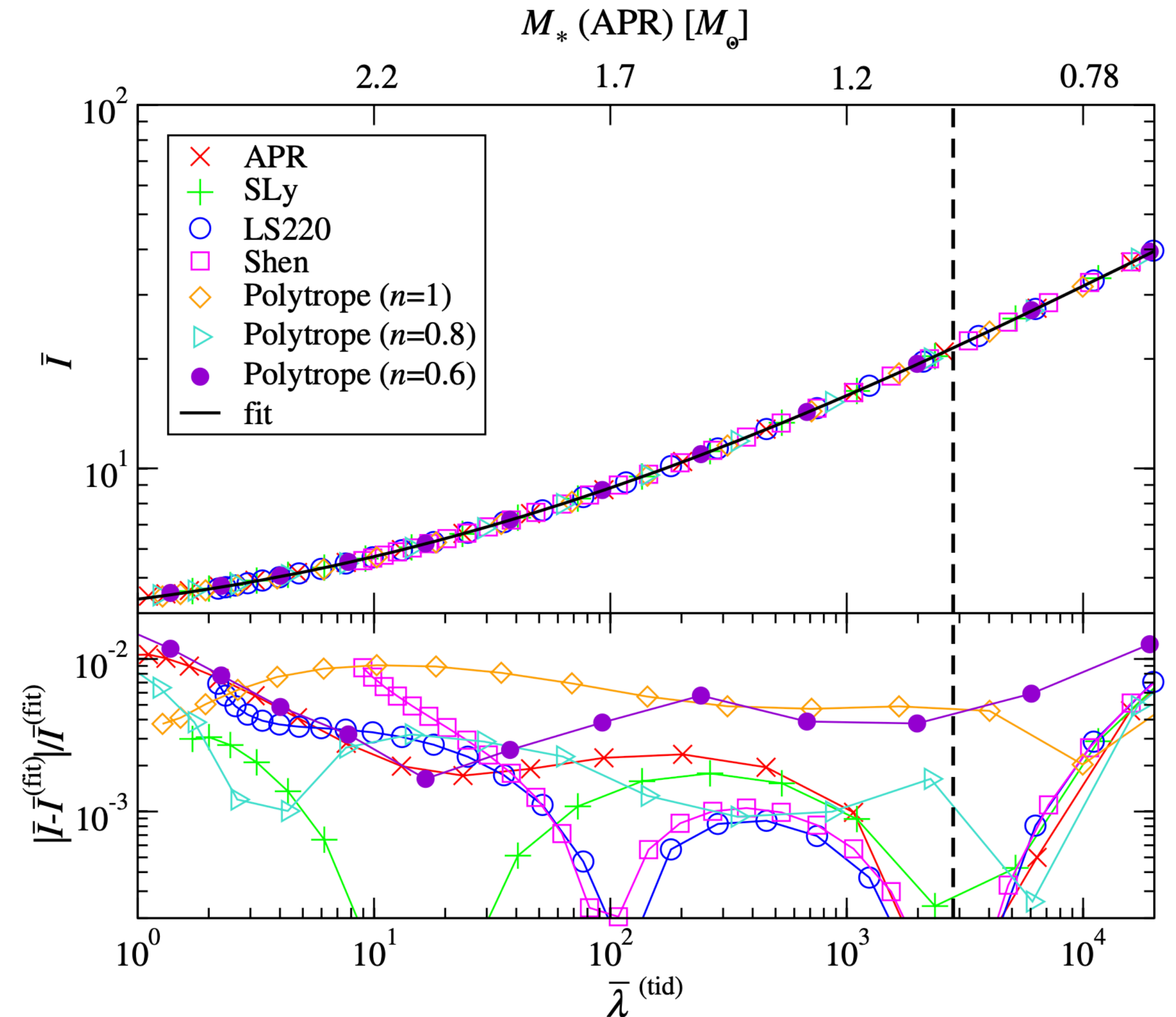
- Moments of inertia (MOI) of neutron star (NS)
 - Build relations between **angular momentum** and **angular velocity**



Credited: ScienceNews

Moment of inertia

- **Moments of inertia (MOI) of neutron star (NS)**
 - Build relations between **angular momentum** and **angular velocity**
- **For Theories**
 - **Structure of NS:** MOI differs under different equation of state (EOS)
 - **Universal relations (I-Love-Q):** Insensitivity to EOS to help us learn gravity



Credited: K. Yagi & N. Yunes, 2013, PRD

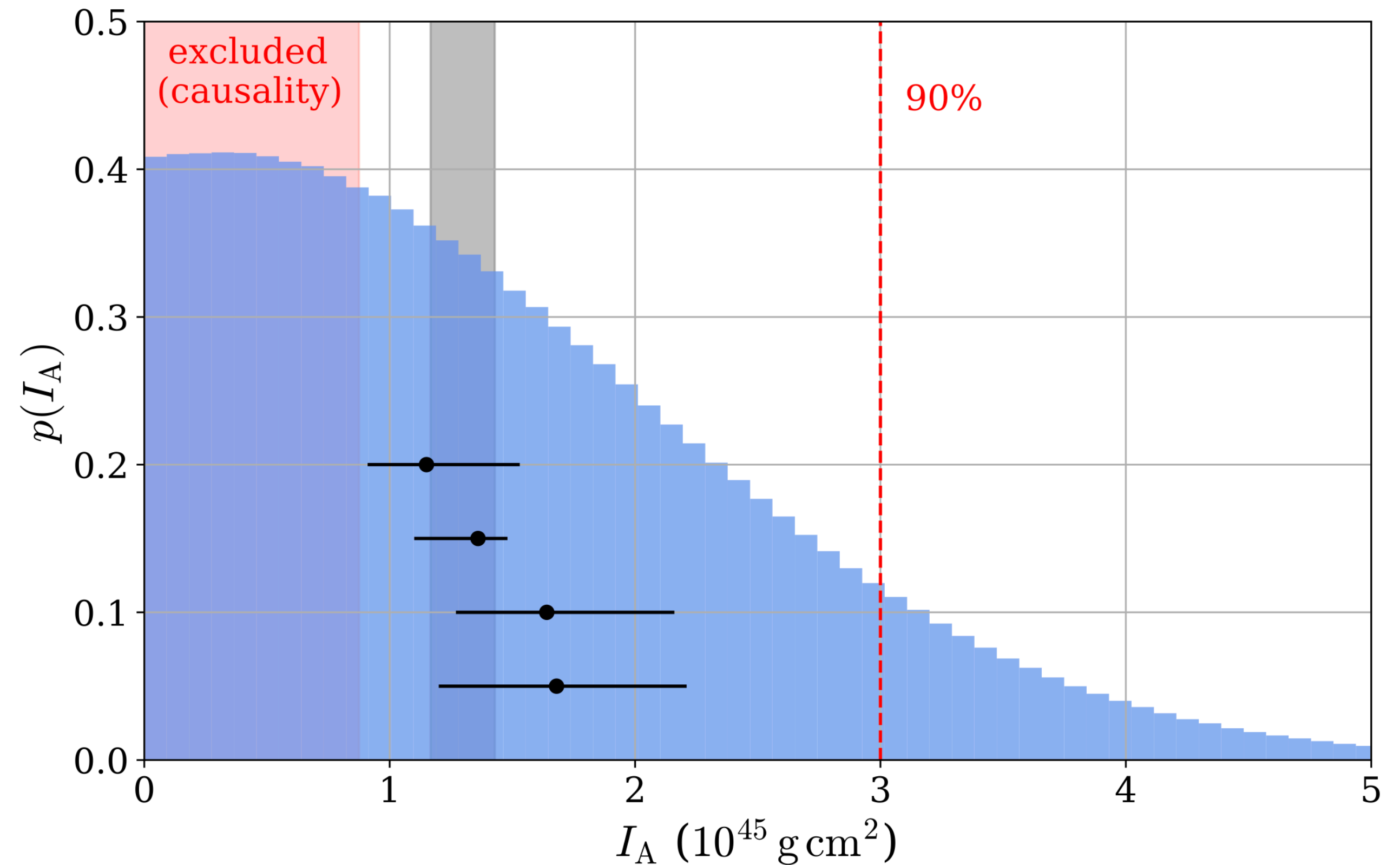
J. B. Hartle, 1967, ApJ

J. B. Hartle & K. S. Thorne, 1968 ApJ

Moment of inertia

- For observations
 - **High precision pulsar timing:** direct detection of MOI from Lense-Thirring effect in pulsar timing

H. Hu et al., 2020, MNRAS



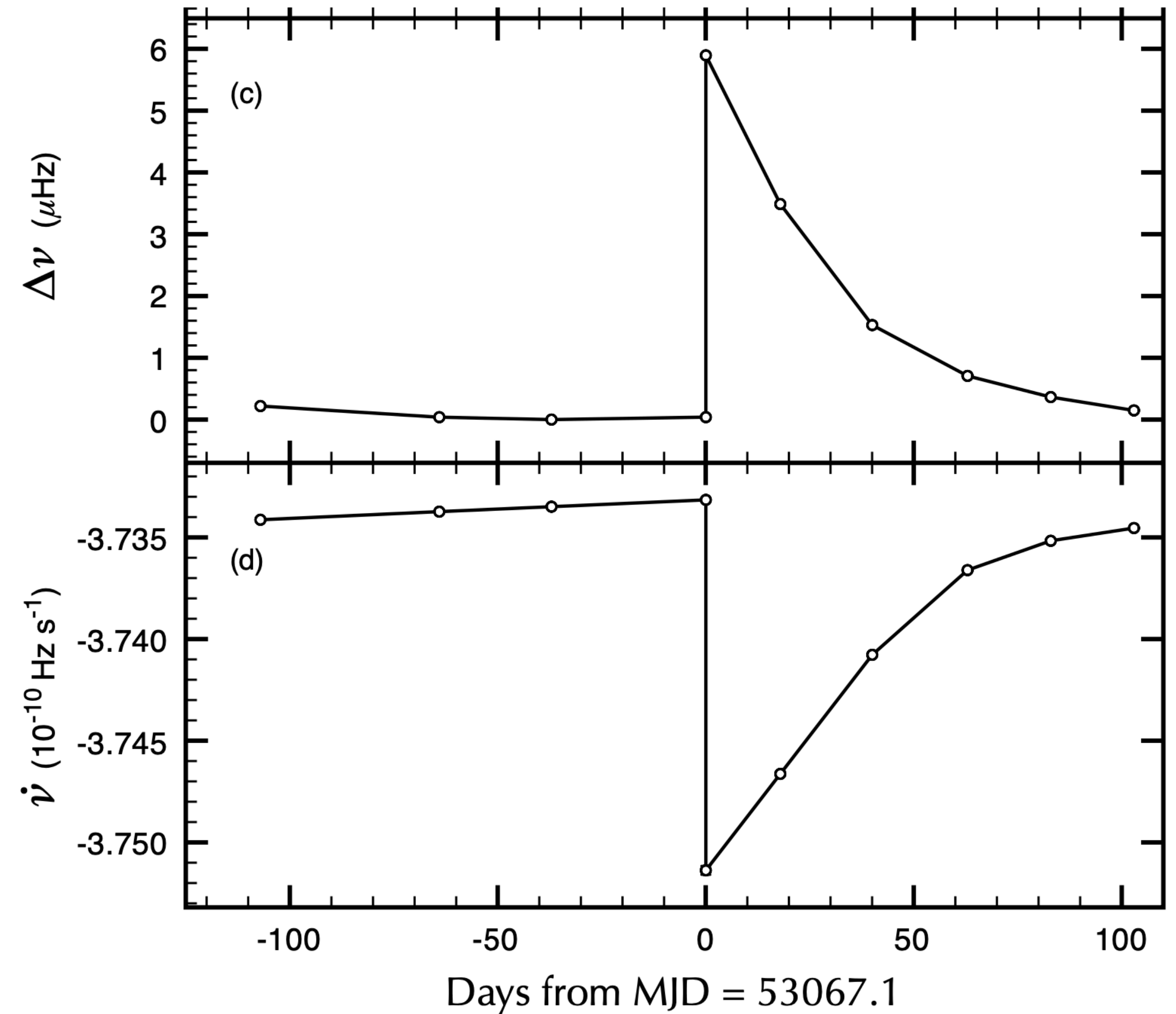
Credited: M. Kramer et al., 2022, PRX

Moment of inertia

- For observations
 - **High precision pulsar timing:** direct detection of MOI from Lense-Thirring effect in pulsar timing
H. Hu et al., 2020, MNRAS
 - **Glitch:** timing irregularities in pulsar timing observation
 - Changes in MOI will result in variations in angular velocity

N. Andersson et al., 2003, PRL
X. Y. Lai et al., 2023, MNRAS

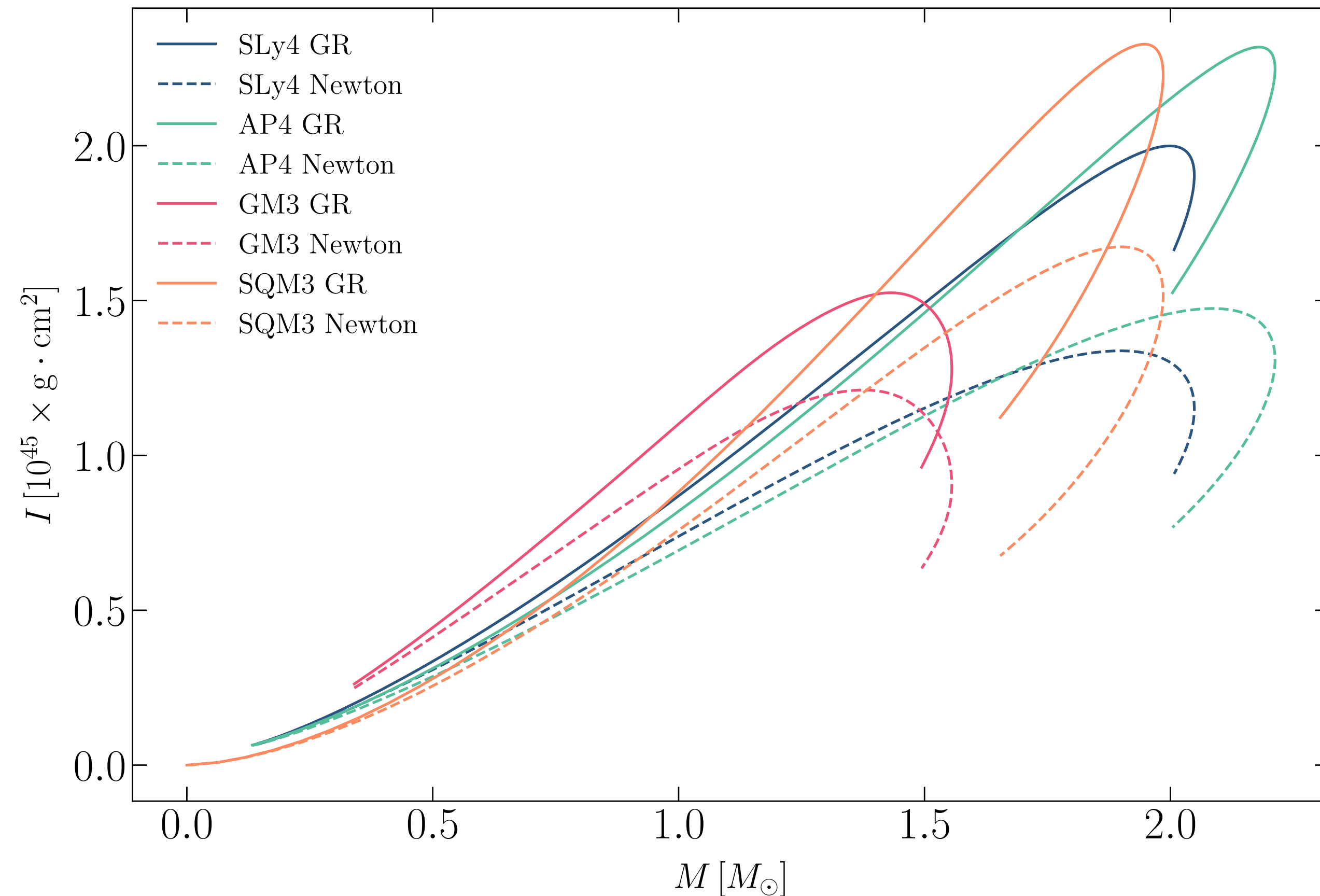
Glitch data of PSR B0531+21 (Crab pulsar)



Credited: C. M. Espinoza et al., 2010, MNRAS

Calculation of moment of inertia

- Moments of inertia of **spherically symmetric** neutron stars in GR
- Solve the perturbed **Einstein's field equation**
- For same density distribution, Newton or GR give **different results**



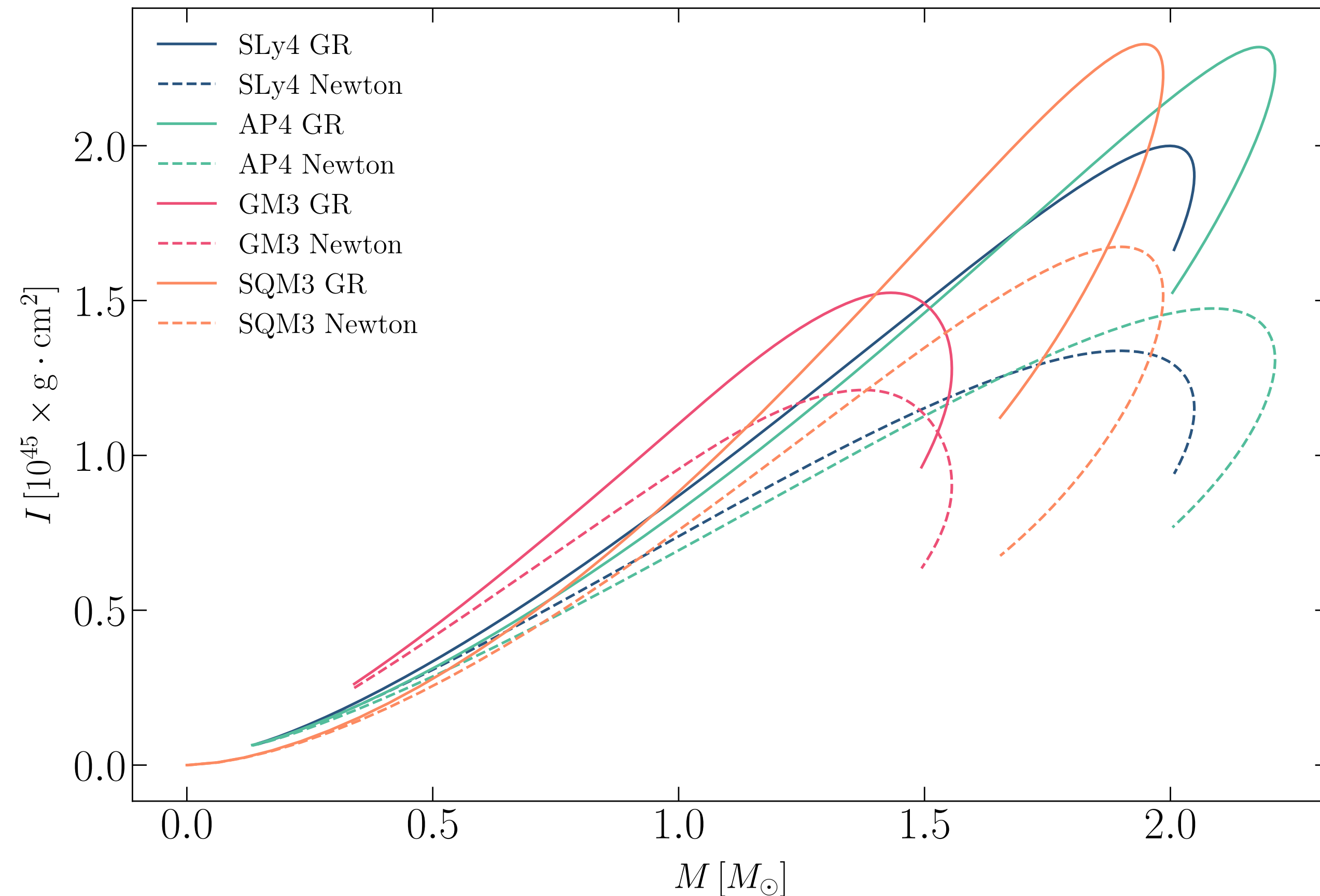
J. B. Hartle, 1967, ApJ

J. B. Hartle & K. S. Thorne, 1968 ApJ

Calculation of moment of inertia

- Moments of inertia of **spherically symmetric** neutron stars in GR
 - Solve the perturbed **Einstein's field equation**
 - For same density distribution, Newton or GR give **different results**

A consistent approach to calculate MOI of axisymmetric NS numerically



J. B. Hartle, 1967, ApJ

J. B. Hartle & K. S. Thorne, 1968 ApJ

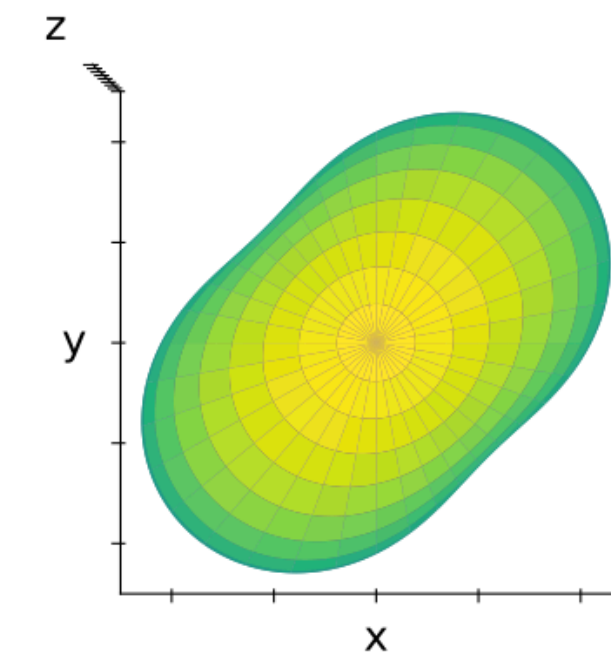
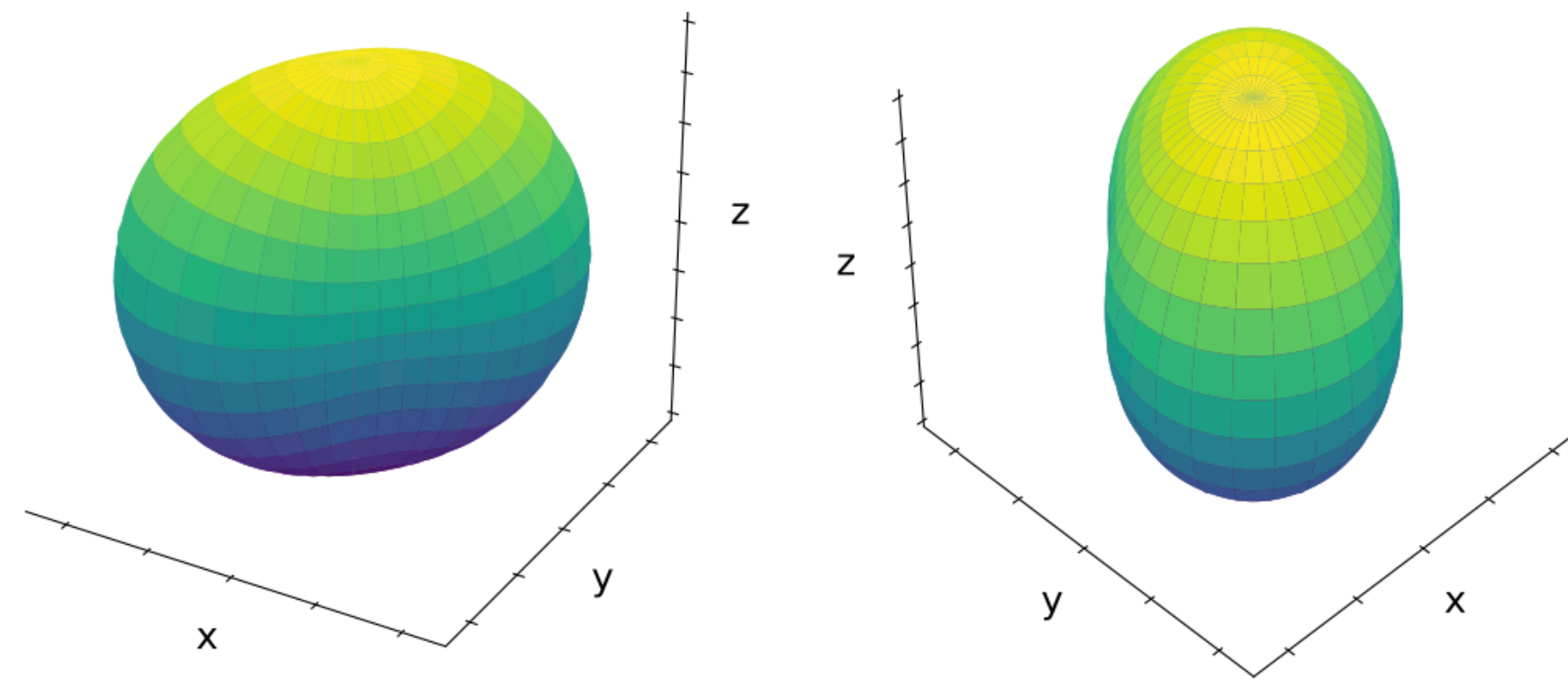
Standard-Model Extension (SME)

- Effective field theory that involve operators for Lorentz violation

$$\mathcal{L}_{LV}^{(4)} = \frac{1}{16\pi G} \left(-uR + s^{\mu\nu} R_{\mu\nu}^T + t^{\alpha\beta\gamma\delta} C_{\alpha\beta\gamma\delta} \right)$$

- The neutron stars have a preferred direction

Q. G. Bailey & V. A. Kostelecký', 2006, PRD



Credited: R. Xu et al., 2020, PLB

Calculations

MOI for spherical NSs in GR

MOI for axisymmetric NSs in SME

Results

Moment of inertia in GR

- Stationary and axially symmetric metric,

$$ds^2 = -H^2 dt^2 + Q^2 dr^2 + r^2 K^2 [d\theta^2 + \sin^2 \theta (d\varphi - L dt)^2]$$

- Field equation,

$$R_{\varphi}^t = 8\pi T_{\varphi}^t$$

4-velocity

$$u^r = u^{\theta} = 0, \quad u^{\varphi} = \Omega u^t$$

Slowly rotation,

$$L(r, \theta) = \omega(r, \theta) + \mathcal{O}(\Omega^3)$$

Moment of inertia in GR

- Stationary and axially symmetric metric,

$$ds^2 = -H^2 dt^2 + Q^2 dr^2 + r^2 K^2 [d\theta^2 + \sin^2 \theta (d\varphi - L dt)^2]$$

- Field equation,

$$R_{\varphi}^t = 8\pi T_{\varphi}^t$$

- Further (partial differential equation, PDE),

$$\frac{1}{r^4} \frac{\partial}{\partial r} \left(r^4 j \frac{\partial \bar{\omega}}{\partial r} \right) + \frac{4}{r} \frac{dj}{dr} \bar{\omega} + \frac{e^{(\lambda-\nu)/2}}{r^2} \frac{1}{\sin^3 \theta} \frac{\partial}{\partial \theta} \left(\sin^3 \theta \frac{\partial \bar{\omega}}{\partial \theta} \right) = 0$$

4-velocity

$$u^r = u^{\theta} = 0, \quad u^{\varphi} = \Omega u^t$$

Slowly rotation,

$$L(r, \theta) = \omega(r, \theta) + \mathcal{O}(\Omega^3)$$

Frame dragging,

$$\bar{\omega} = \Omega - \omega(r, \theta)$$

Moment of inertia in GR

- Stationary and axially symmetric metric,

$$ds^2 = -H^2 dt^2 + Q^2 dr^2 + r^2 K^2 [d\theta^2 + \sin^2 \theta (d\varphi - L dt)^2]$$

- Field equation,

$$R_{\varphi}^t = 8\pi T_{\varphi}^t$$

- Further (partial differential equation, PDE),

$$\frac{1}{r^4} \frac{\partial}{\partial r} \left(r^4 j \frac{\partial \bar{\omega}}{\partial r} \right) + \frac{4}{r} \frac{dj}{dr} \bar{\omega} + \frac{e^{(\lambda-\nu)/2}}{r^2} \frac{1}{\sin^3 \theta} \frac{\partial}{\partial \theta} \left(\sin^3 \theta \frac{\partial \bar{\omega}}{\partial \theta} \right) = 0$$

- For spherical NS in GR,

$$\frac{1}{r^4} \frac{d}{dr} \left(r^4 j \frac{d\bar{\omega}}{dr} \right) + \frac{4}{r} \frac{dj}{dr} \bar{\omega} = 0$$

4-velocity

$$u^r = u^\theta = 0, \quad u^\varphi = \Omega u^t$$

Slowly rotation,

$$L(r, \theta) = \omega(r, \theta) + \mathcal{O}(\Omega^3)$$

Frame dragging,

$$\bar{\omega} = \Omega - \omega(r, \theta)$$

Spherical NS in GR,

$$\bar{\omega}(r) = \Omega - \frac{2J}{r^3}$$

$$I = J/\Omega$$

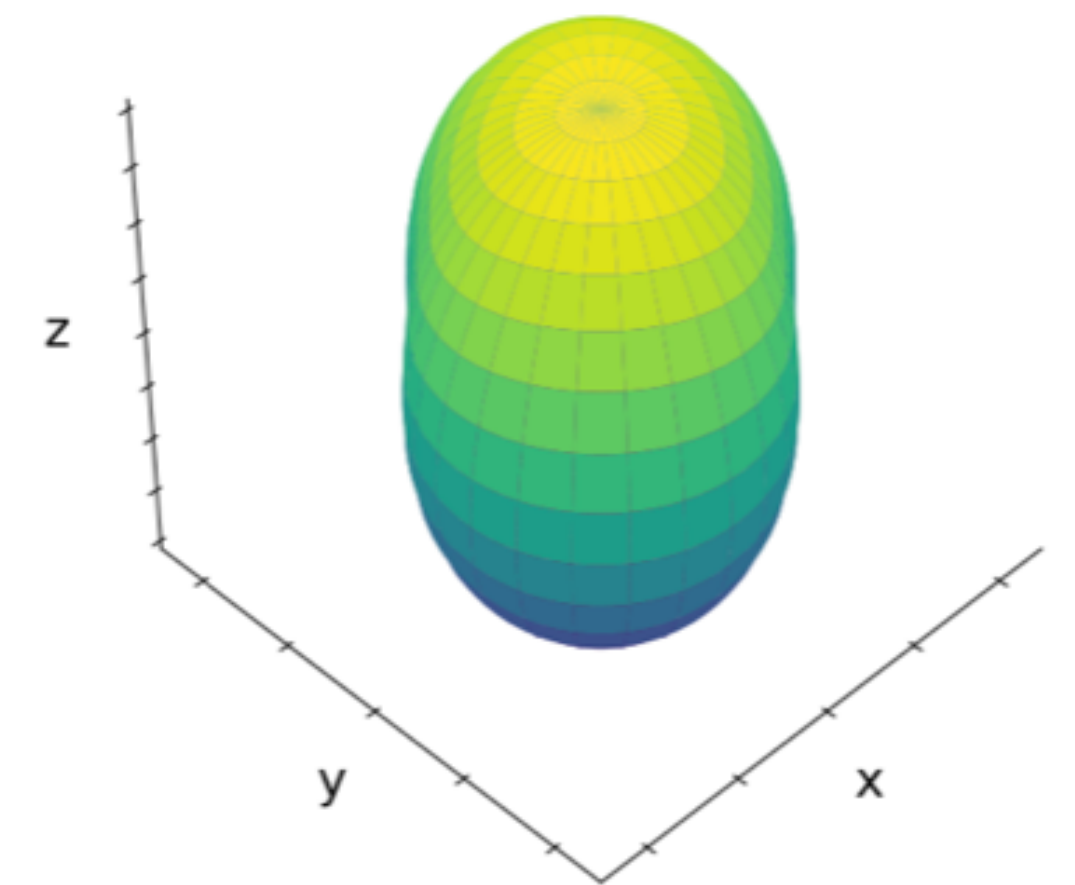
J. B. Hartle, 1967, ApJ

J. B. Hartle & K. S. Thorne, 1968 ApJ

Moment of inertia in SME

- We still want to calculate this field equation, but there's some difference
 - **Difference 1: field equation has another term**
 - We should solve $R_{\varphi}^t = 8\pi T_{\varphi}^t - V_{\varphi}^t$, where $V_{\nu}^{\mu} = \bar{s}^{\alpha\beta} g^{\mu\delta} G_{\delta\alpha\beta\nu}$

Q. G. Bailey et al., 2014, PRD



R. Xu et al., 2020, PLB

Moment of inertia in SME

- We still want to calculate this field equation, but there's some difference

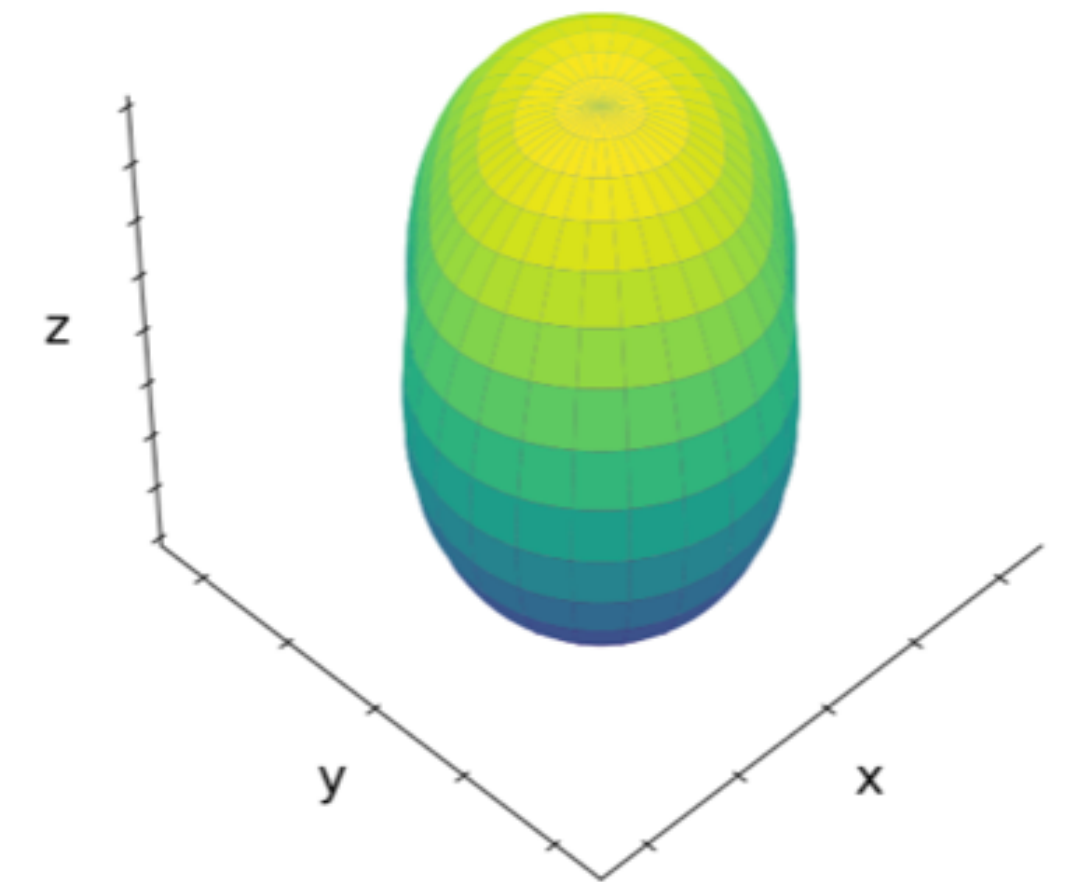
- **Difference 1: field equation has another term**

- We should solve $R_\varphi^t = 8\pi T_\varphi^t - V_\varphi^t$, where $V_\nu^\mu = \bar{s}^{\alpha\beta} g^{\mu\delta} G_{\delta\alpha\beta\nu}$

Q. G. Bailey et al., 2014, PRD

- **Difference 2: axisymmetric deformation of neutron stars**

- $\rho^{(1)}(r, \theta) = -\frac{1}{6}\bar{s}^{zz}(3\cos^2\theta - 1)r\rho^{(0)}(r),_r$
- $P^{(1)}(r, \theta) = -\frac{1}{6}\bar{s}^{zz}(3\cos^2\theta - 1)rP^{(0)}(r),_r$



R. Xu et al., 2020, PLB

Moment of inertia in SME

- We still want to calculate this field equation, but there's some difference

- **Difference 1: field equation has another term**

- We should solve $R_{\varphi}^t = 8\pi T_{\varphi}^t - V_{\varphi}^t$, where $V_{\nu}^{\mu} = \bar{s}^{\alpha\beta} g^{\mu\delta} G_{\delta\alpha\beta\nu}$

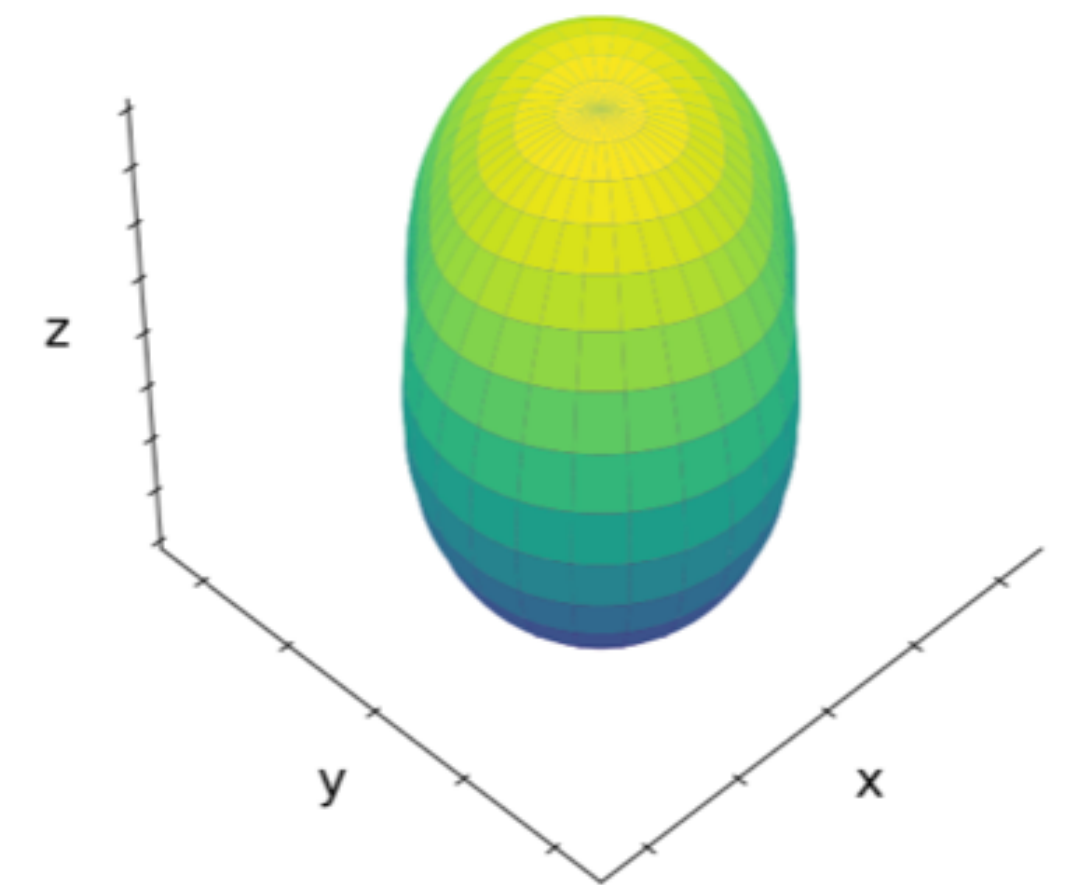
Q. G. Bailey et al., 2014, PRD

- **Difference 2: axisymmetric deformation of neutron stars**

- $\rho^{(1)}(r, \theta) = -\frac{1}{6}\bar{s}^{zz}(3\cos^2\theta - 1)r\rho^{(0)}(r),_r$

- $P^{(1)}(r, \theta) = -\frac{1}{6}\bar{s}^{zz}(3\cos^2\theta - 1)rP^{(0)}(r),_r$

$$\frac{1}{r^4} \frac{\partial}{\partial r} \left(r^4 j \frac{\partial \bar{\omega}}{\partial r} \right) + \frac{4}{r} \frac{dj}{dr} \bar{\omega} + \frac{e^{(\lambda-\nu)/2}}{r^2} \frac{1}{\sin^3 \theta} \frac{\partial}{\partial \theta} \left(\sin^3 \theta \frac{\partial \bar{\omega}}{\partial \theta} \right) = S'_1(r, \theta) + S'_2(r, \theta)$$



R. Xu et al., 2020, PLB

Solve PDE numerically

$$\frac{1}{r^4} \frac{\partial}{\partial r} \left(r^4 j \frac{\partial \bar{\omega}}{\partial r} \right) + \frac{4}{r} \frac{dj}{dr} \bar{\omega} + \frac{e^{(\lambda-\nu)/2}}{r^2} \frac{1}{\sin^3 \theta} \frac{\partial}{\partial \theta} \left(\sin^3 \theta \frac{\partial \bar{\omega}}{\partial \theta} \right) = S'_1(r, \theta) + S'_2(r, \theta)$$

- **How to get MOI?**

- Far field behaviors of $\bar{\omega}$
- Solve PDE for $r \in (0, \infty)$

$$\bar{\omega}(r) = \Omega - \frac{2J}{r^3}$$

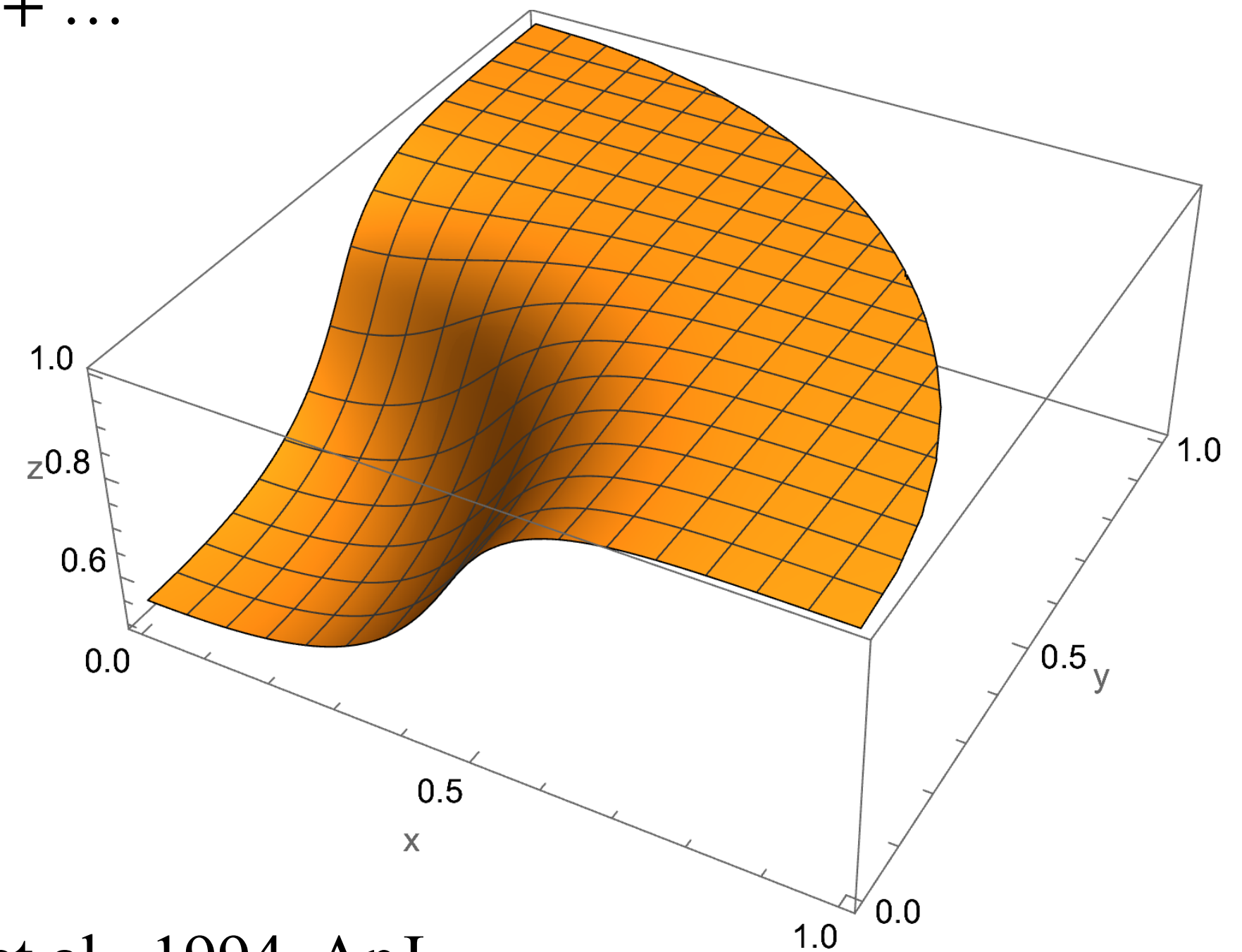
$$\bar{\omega}(r, \theta) = A + \frac{B(\theta)}{r^3} + \frac{C(\theta)}{r^4} + \dots$$

- **Finite element method**

- Numerically, integrating r to infinity is impossible

- Change of variables $(r, \theta) \rightarrow \left(x \equiv \frac{r \cos \theta}{r + R}, y \equiv \frac{r \sin \theta}{r + R} \right)$

- Improve accuracy greatly



Solve PDE numerically

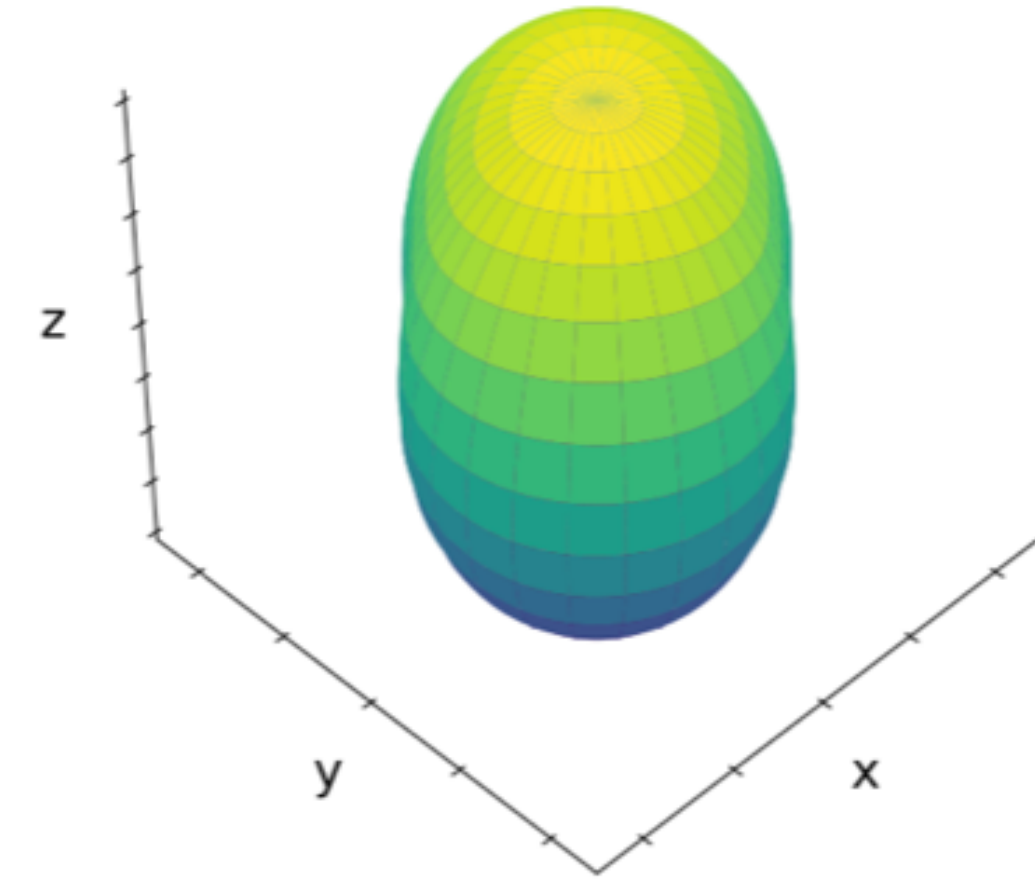
- **Process of numerical solving**

- Derive the modified PDE of MOI
- Change of variables

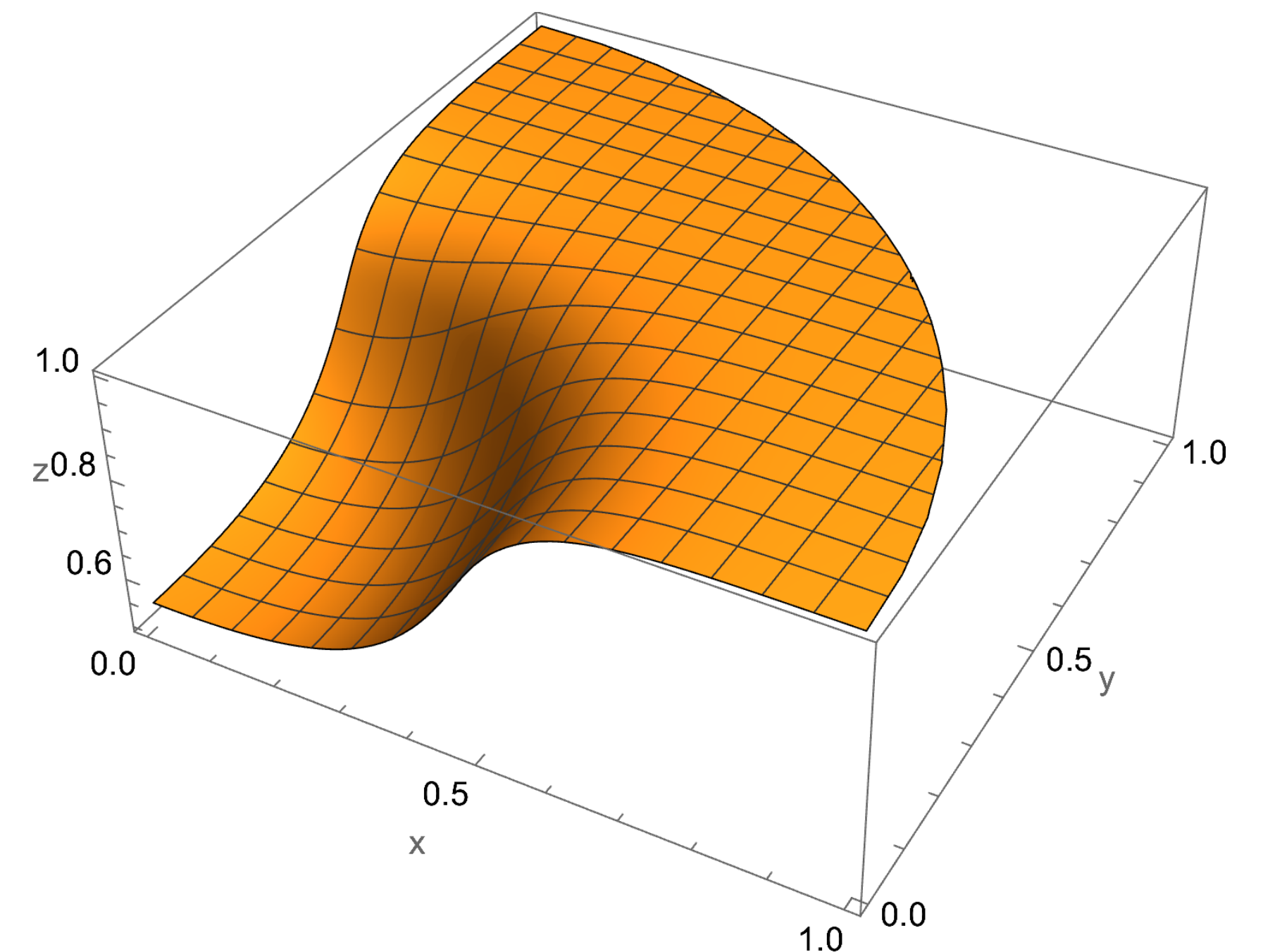
$$(r, \theta) \rightarrow \left(x \equiv \frac{r \cos \theta}{r + R}, y \equiv \frac{r \sin \theta}{r + R} \right)$$

- Solve (x, y) PDE to get numerical solution
- Fitting with polynomial to get MOI with far field behaviors of $\bar{\omega}$

$$\bar{\omega}(r, \theta) = A + \frac{B(\theta)}{r^3} + \frac{C(\theta)}{r^4} + \dots$$

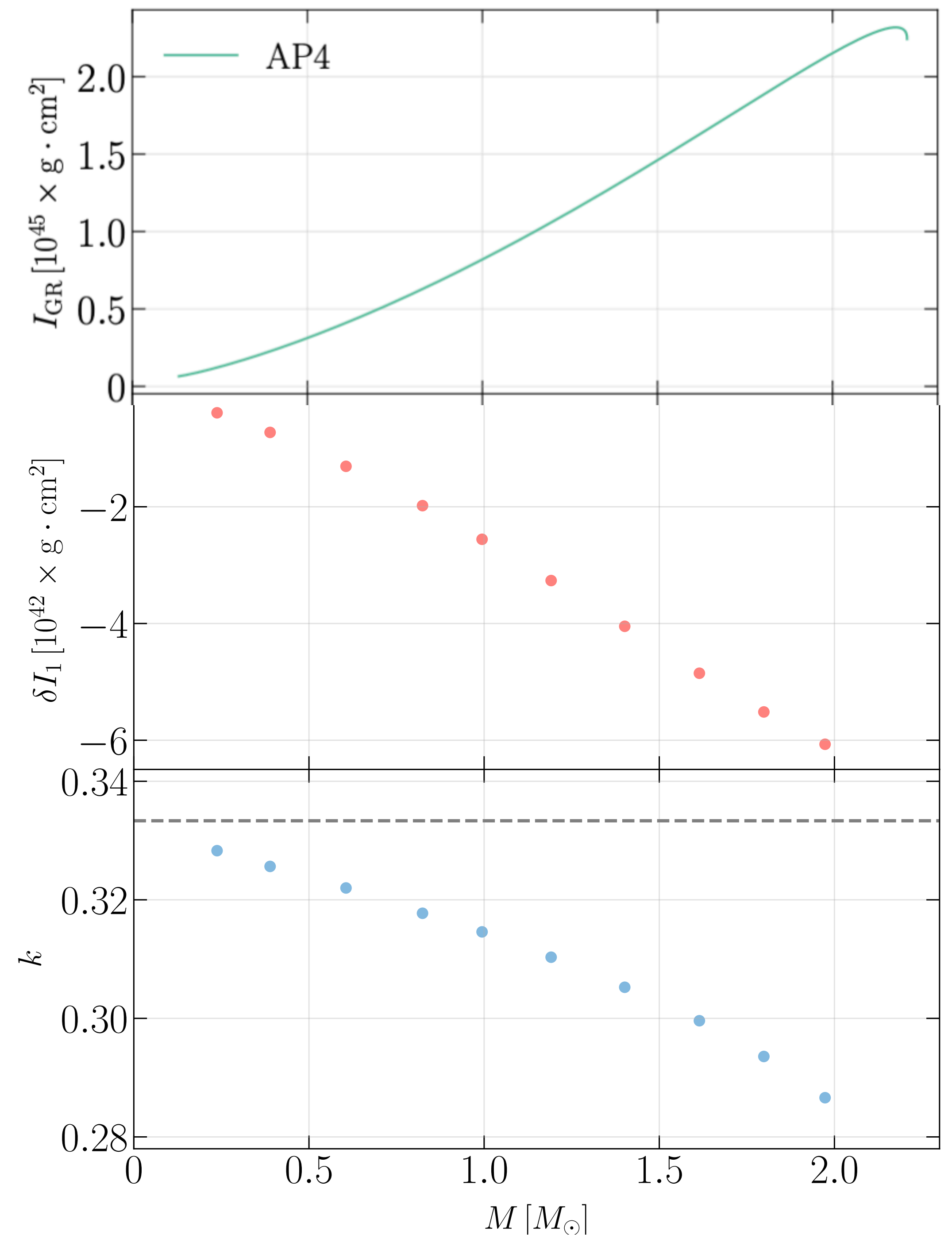


R. Xu et al., 2020, PLB



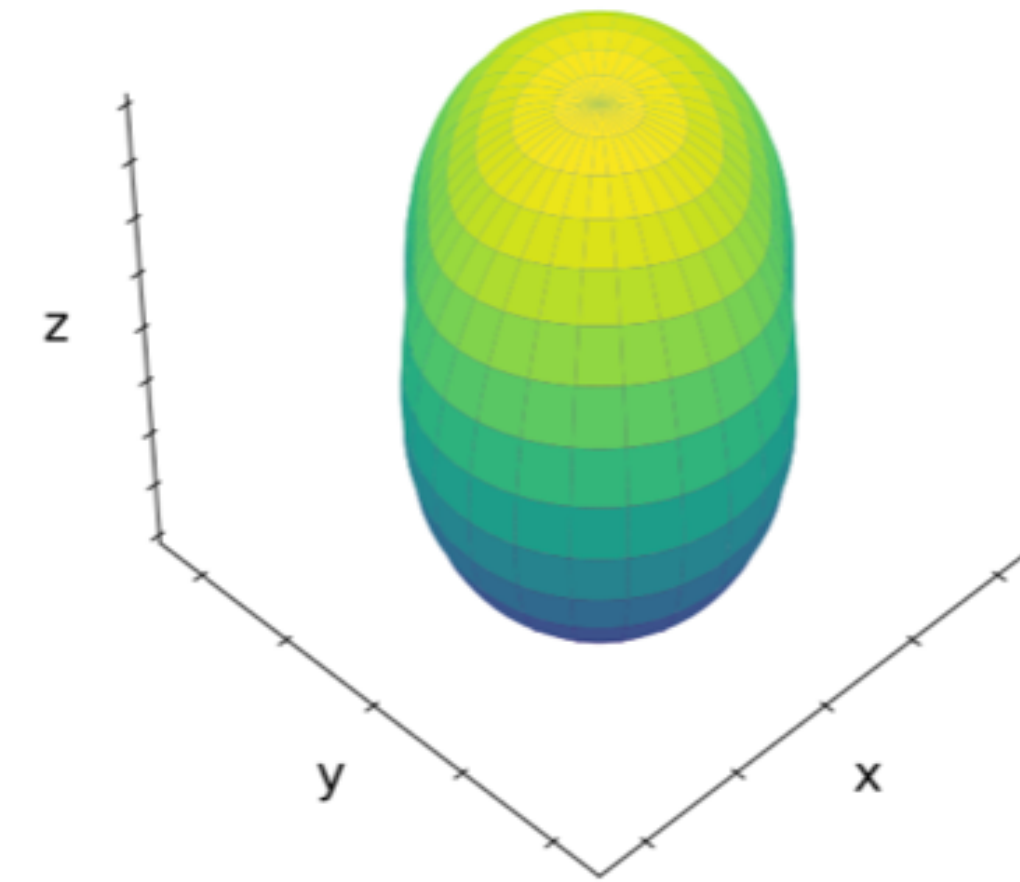
Results

- Corrections to MOIs **caused by axisymmetric deformations**
 - $k = \delta I_1 / I$, for chosen deformations it is 1/3
 - For deformation caused by Lorentz violation,
 - **Ratio $k = \delta I_1 / I$ from GR differs from Newtonian one**
 - **For a neutron star with $1.4 M_\odot$, it is 8 %**

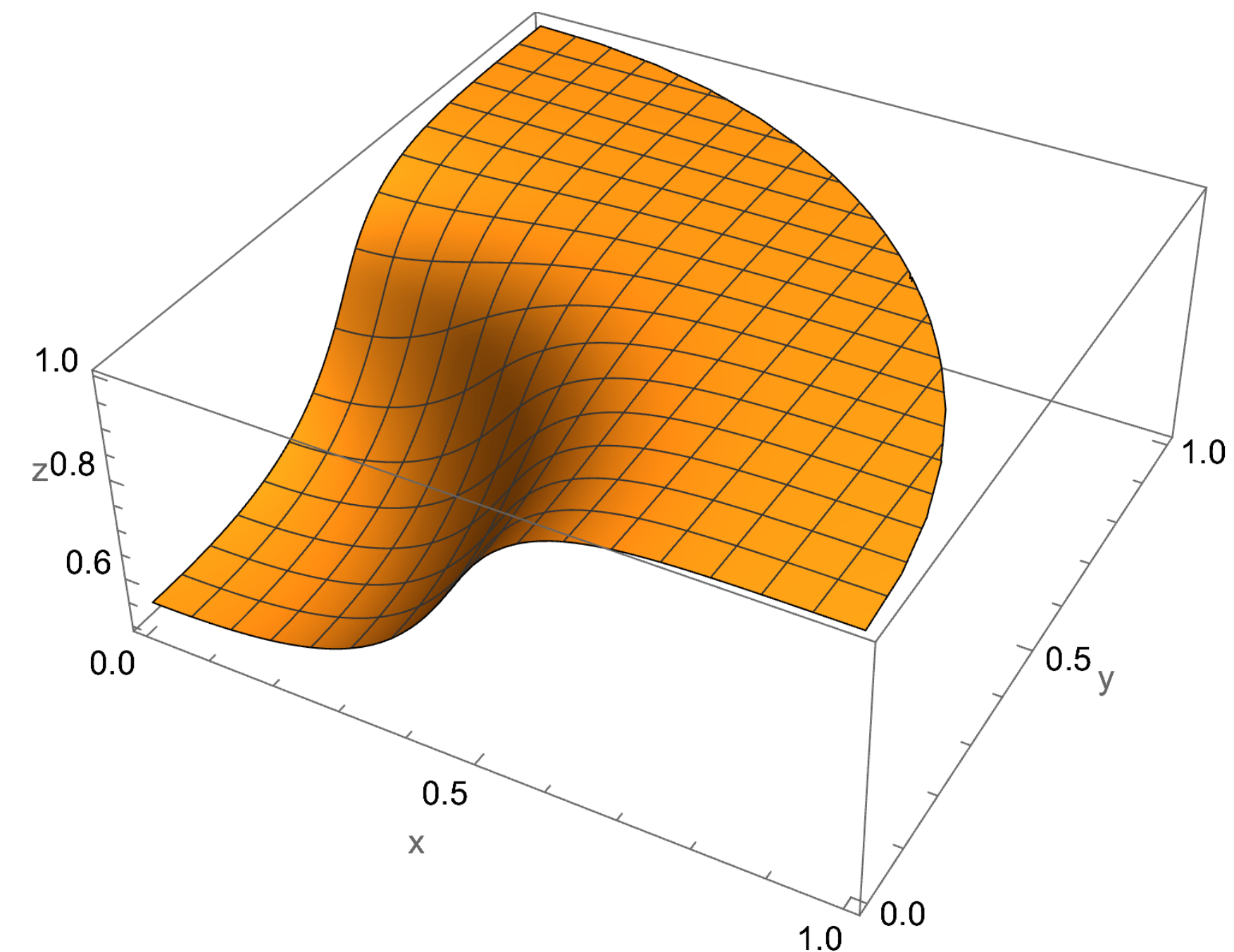


Summary

- We develop a **consistent approach** to calculate moment of inertia for **axisymmetric** neutron stars in the Standard-Model Extension
 - **Finite element method**
 - **Ratio $k = \delta I_1 / I$ from GR differs from Newtonian one**
 - **For a neutron star with $1.4 M_{\odot}$, it is 8 %**



R. Xu et al., 2020, PLB



Thanks!